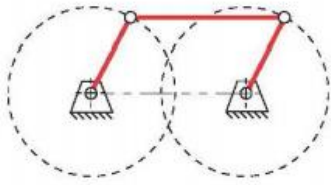


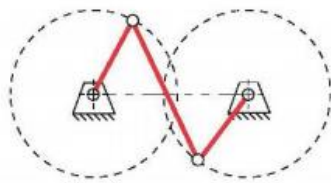
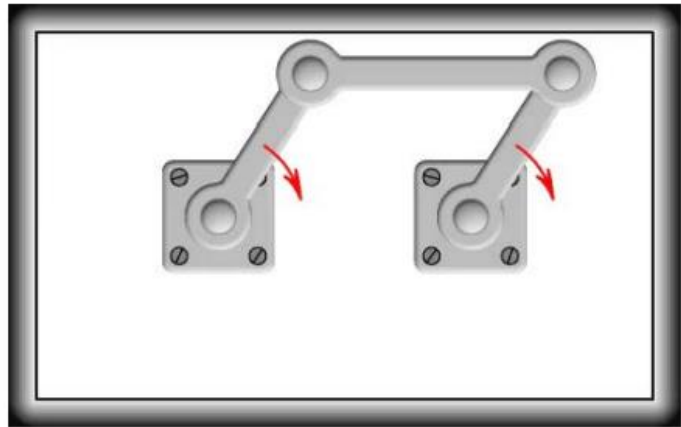
Problems

Calculate the degree of freedom
For next problems mechanisms

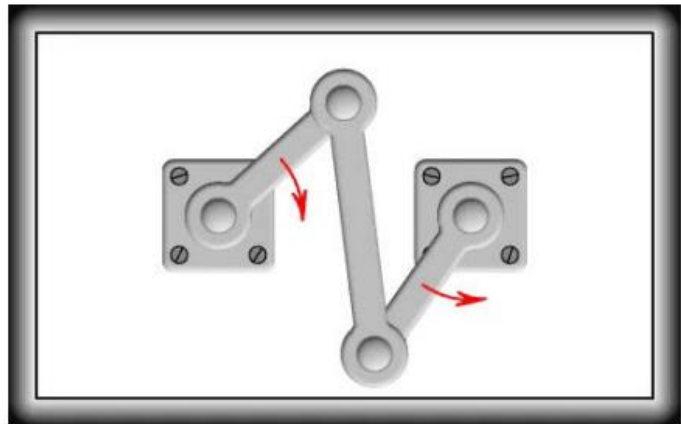
Four-bar linkage examples



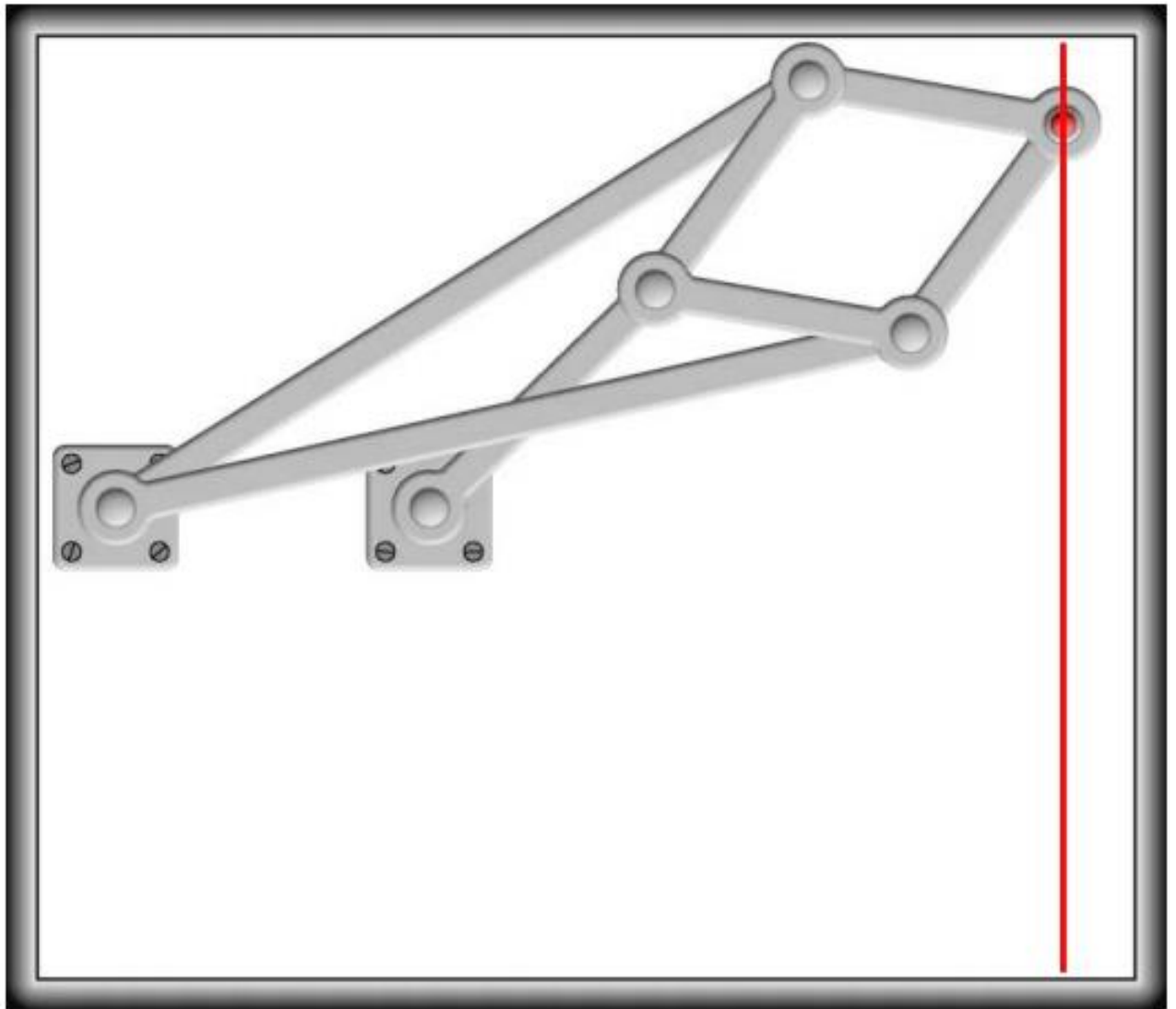
Parallel 4-bar

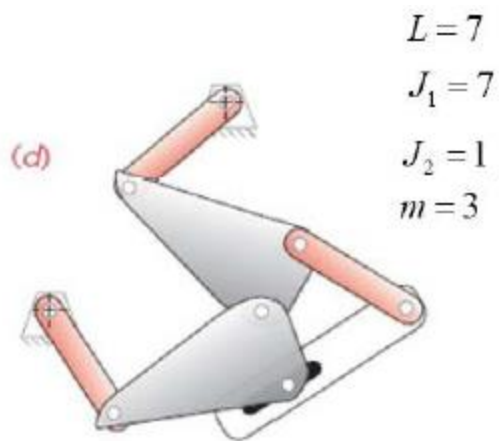
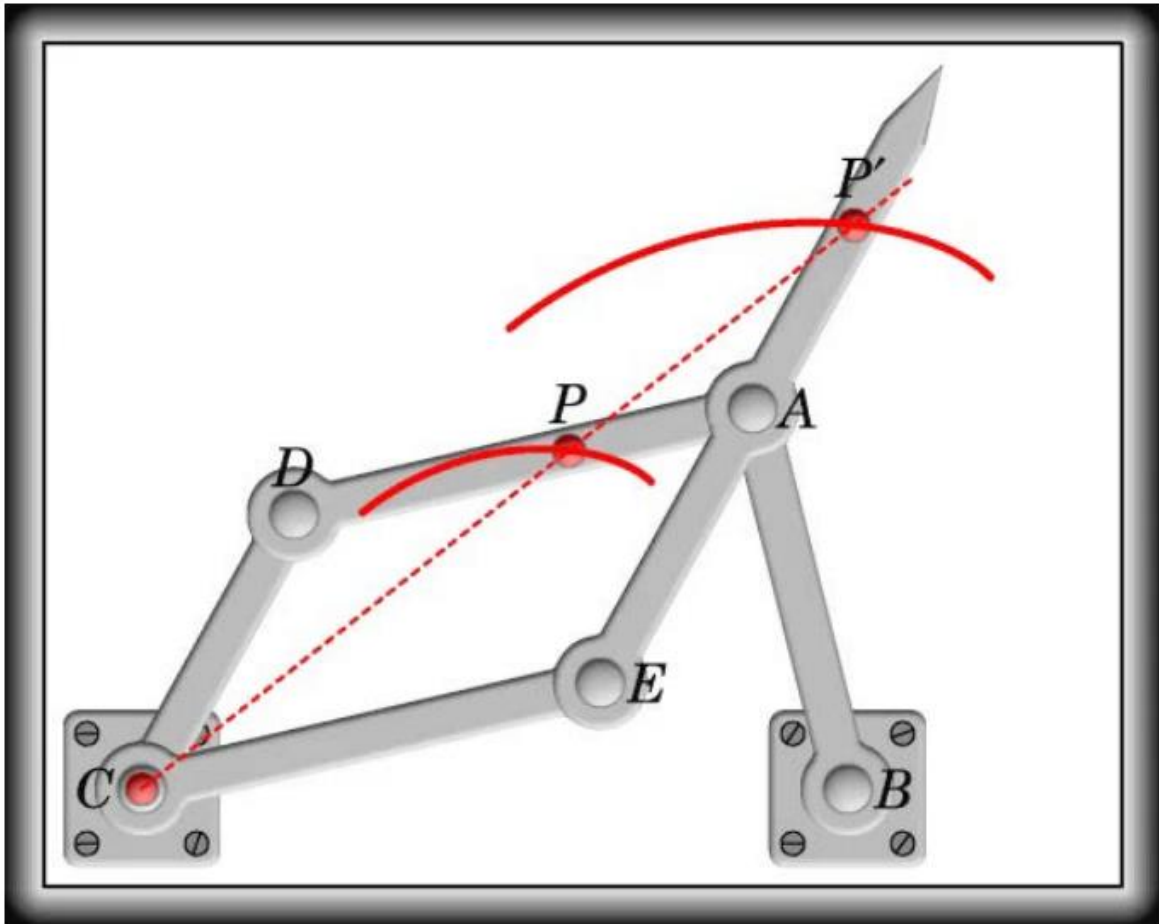


Anti-parallel 4-bar



Straight- line linkages (Peaucellier)





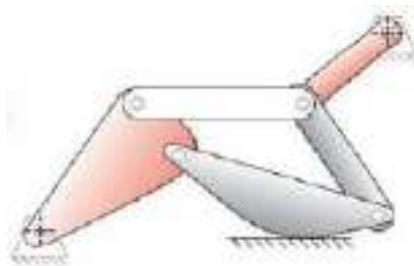
$$\begin{aligned}
 L &= 7, j_1 = 7, j_2 = 1 \\
 m &= 3(L - 1) - 2j_1 - j_2 \\
 m &= 3(7 - 1) - 2 \times 7 - 1 = 3 \text{ DOF}
 \end{aligned}$$



$$L = 4, j_1 = 4, j_2 = 0$$

$$m = 3(L - 1) - 2j_1 - j_2$$

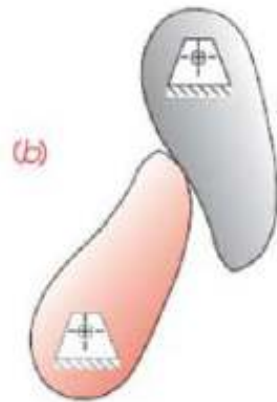
$$m = 3(4 - 1) - 2 \times 4 - 0 = 1 \text{ } DOF$$



$$L = 6, j_1 = 7, j_2 = 1$$

$$m = 3(L - 1) - 2j_1 - j_2$$

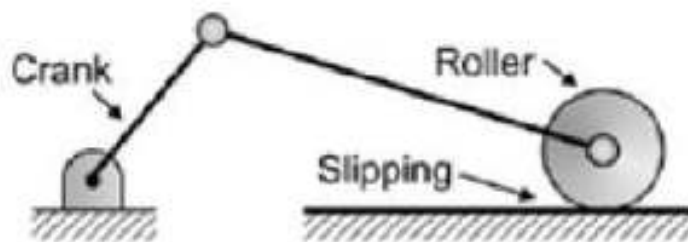
$$m = 3(6 - 1) - 2 \times 7 - 1 = 0 \text{ } DOF$$



$$L = 3, j_1 = 2, j_2 = 1$$

$$m = 3(L - 1) - 2j_1 - j_2$$

$$m = 3(3 - 1) - 2 \times 2 - 1 = 1 \text{ DOF}$$

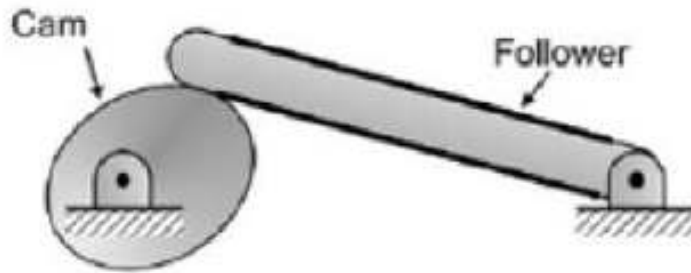


$$L = 4, j_1 = 3, j_2 = 1 \text{ since there is slipping}$$

$$m = 3(L - 1) - 2j_1 - j_2$$

$$m = 3(4 - 1) - 2 \times 3 - 1 = 2 \text{ DOF}$$

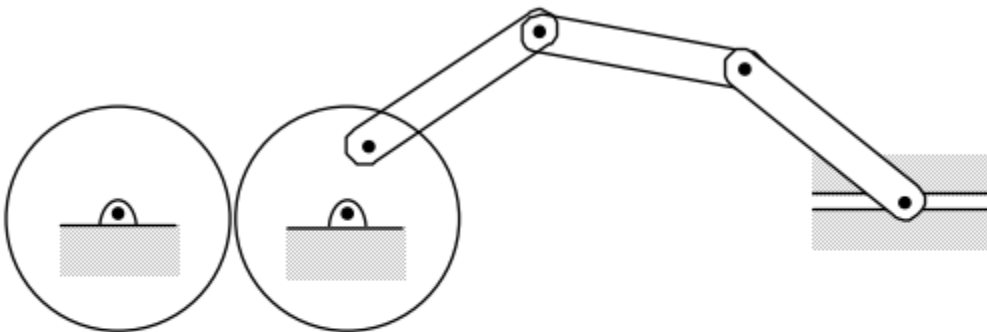
Find the mobility for the following mechanisms?



$$L = 3, j_1 = 2, j_2 = 1$$

$$m = 3(L - 1) - 2j_1 - j_2$$

$$m = 3(3 - 1) - 2 \times 2 - 1 = 1 \text{ DOF}$$

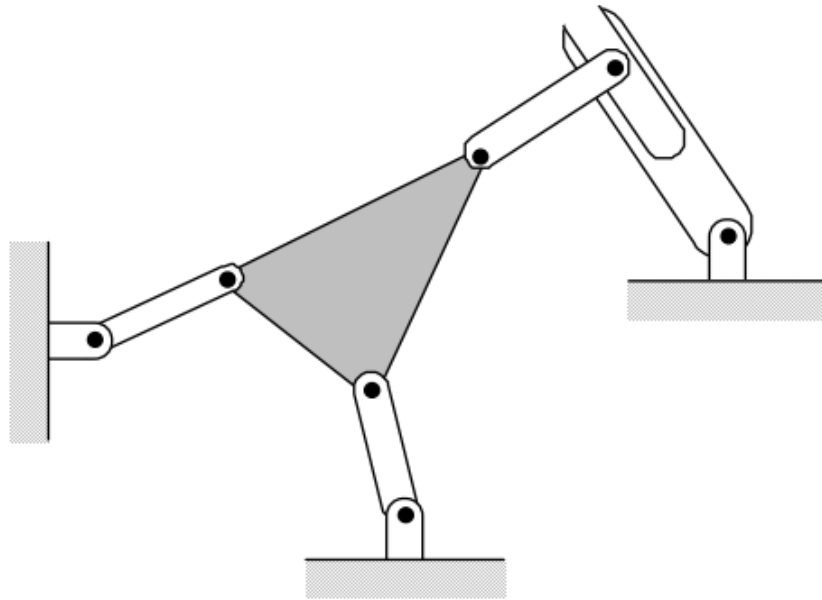


$$n=6$$

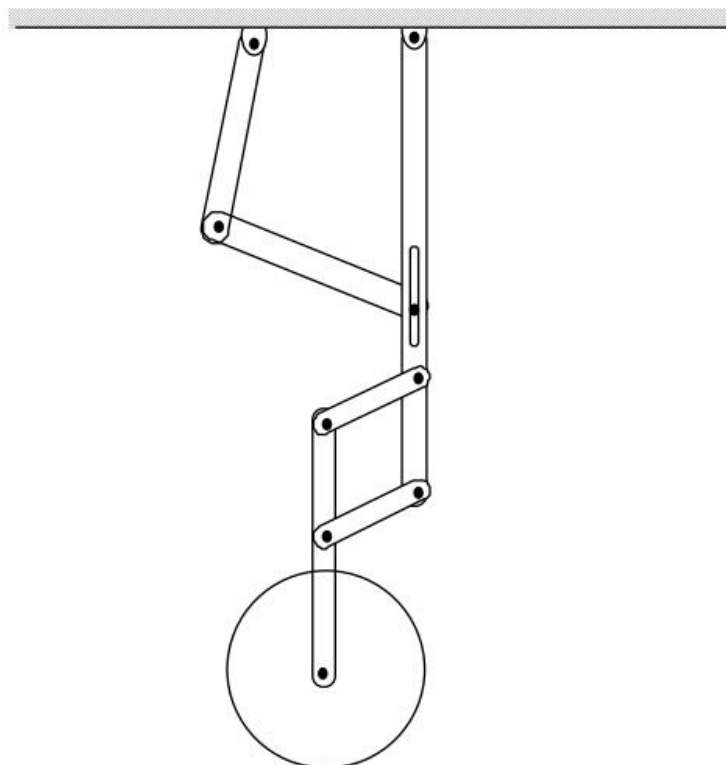
$$J_1=5$$

$$J_2=2$$

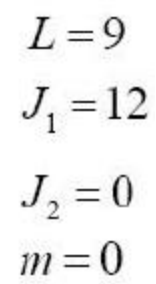
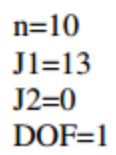
$$\text{DOF}=3$$

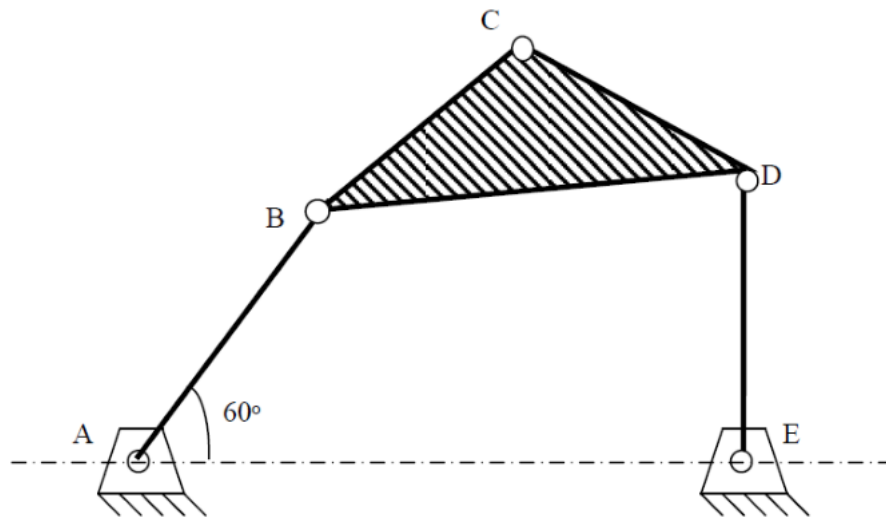


$n=6$
 $J1=6$
 $J2=1$
 $\text{DOF} = 2$

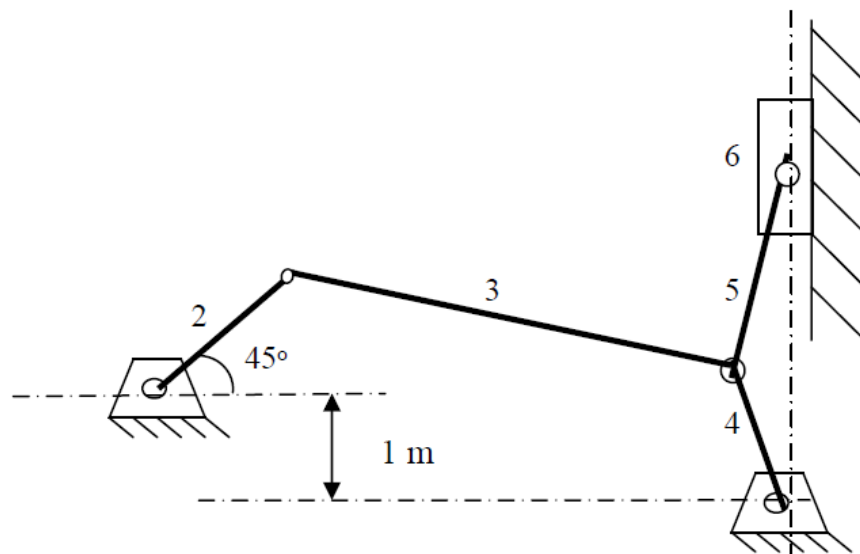


$n=8$
 $J1=8$
 $J2=2$ Note: you might consider the wheel as just 1 dof
 $\text{DOF}= 3$

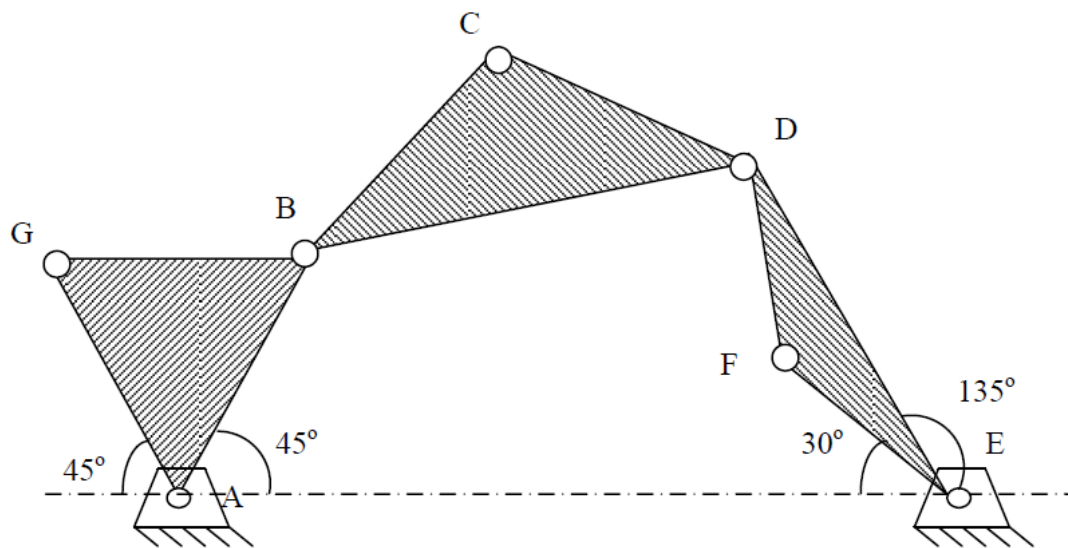




[Given that: $AB = DE = 1 \text{ m}$, $BC = CD = 0.8 \text{ m}$, $AE = 1.5 \text{ m}$]



[Given that: Link 2 = $\sqrt{2} \text{ m}$, Link 3 = 3 m , Link 4 = 1.5 m , Link 5 = 2 m]



[Given that: $AB = AG = 2\sqrt{2}$ m, $BC = CD = 2$ m, $AE = 3\sqrt{2}$ m, $EF = 2$ m]

