

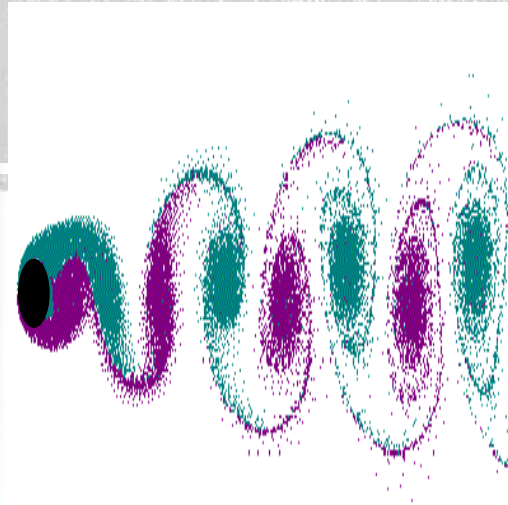


جامعة الإمام عبد الرحمن بن فيصل

IMAM ABDULRAHMAN BIN FAISAL UNIVERSITY

FLUID MECHANICS- ENG 321

Chapter 05_DYNAMICS



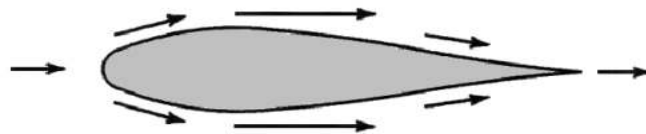
STEADY AND UNSTEADY FLOW

- For a flow that appears the same at all times...

$$\frac{\partial \mathbf{u}}{\partial t} = \mathbf{0}$$

and likewise for all flow properties.

- We call such a flow **steady**.
- We call time-varying flows **unsteady**.
- Observing flow over a wing from your seat on the plane...

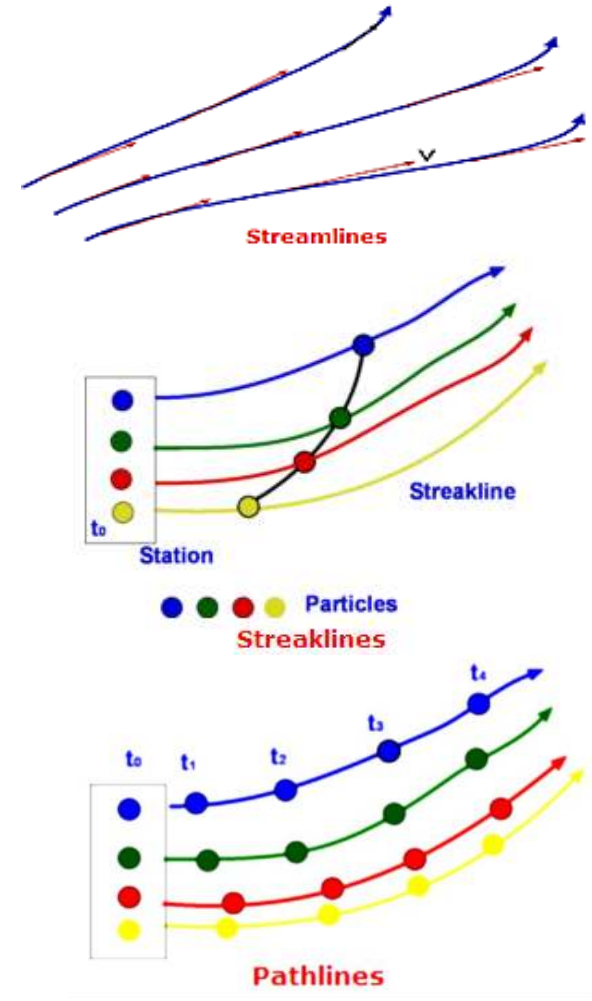


← When the plane is cruising, the flow is steady

- Velocity **is the same** at each point over the wing.
- Velocity **varies** from point to point along the wing.

STREAMLINES, STREAKLINES & PATHLINES

- ❑ **Streamline** is one that drawn tangential to the velocity vector at every point in the flow at a given instant and forms a powerful tool in understanding flows.
- ❑ **Streakline** concentrates on fluid particles that have gone through a fixed station or point. At some instant of time the position of all these particles are marked and a line is drawn through them. Such a line is called a streakline
- ❑ **Pathline** is the line traced by a given particle. This is generated by injecting a dye into the fluid and following its path by photography or other means.



STREAMLINES, STREAKLINES & PATHLINES

- **Streamlines** are contours in a flow field to which the velocity vector is tangent.
- Fluid moves along the streamlines, so they help us visualize a flow field.
- If $d\mathbf{r} = dx \mathbf{i} + dy \mathbf{j} + dz \mathbf{k}$ is a differential vector tangent to the streamline, then its cross product with the velocity vector is zero...

$$\mathbf{u} \times d\mathbf{r} = \mathbf{i}(vdz - wdy) + \mathbf{j}(wdx - udz) + \mathbf{k}(udy - vdx) = \mathbf{0}$$

- Consequently, the differential equation for a streamline is:

$$\frac{dx}{u} = \frac{dy}{v} = \frac{dz}{w}$$

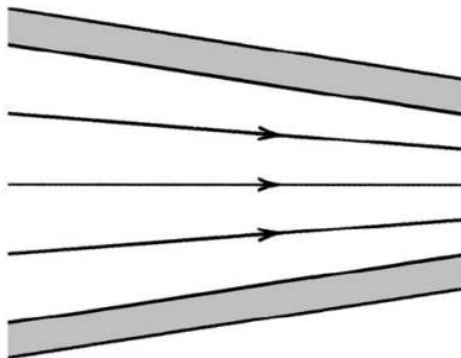
STREAMLINES, STREAKLINES & PATHLINES

- In 2-D, the equation for a streamline is:

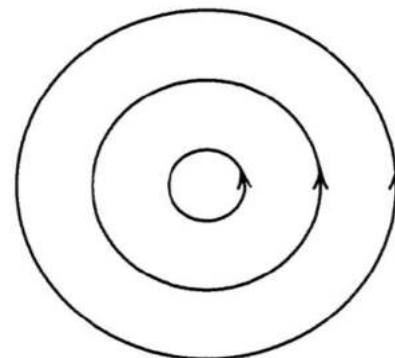
$$\frac{dy}{dx} = \frac{v}{u}$$

which says the **streamline's slope** equals the angle the velocity vector makes to the horizontal.

- Examples of streamlines...



Converging flow



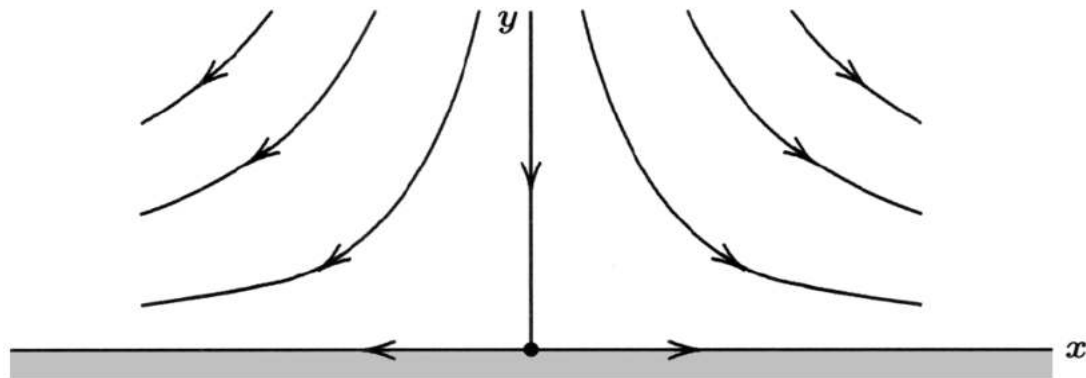
Potential-vortex flow

STREAMLINES, STREAKLINES & PATHLINES

- For **steady flows**, **streamlines** can be observed experimentally by injecting dye, smoke, or other tracer material.
- For **unsteady flows**, injecting tracer material continuously does not display streamlines.
 - Shows the path traveled by all particles that have passed through the injection point...these contours are called **streaklines**.
 - Alternatively, a time-exposure photograph of a marked fluid particle shows the Lagrangian coordinates of the particle...this is called a **pathline**.
- Streamlines, streaklines and pathlines are identical for steady flows

STREAMLINES, STREAKLINES & PATHLINES

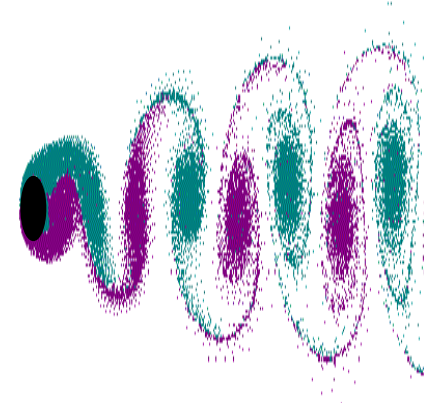
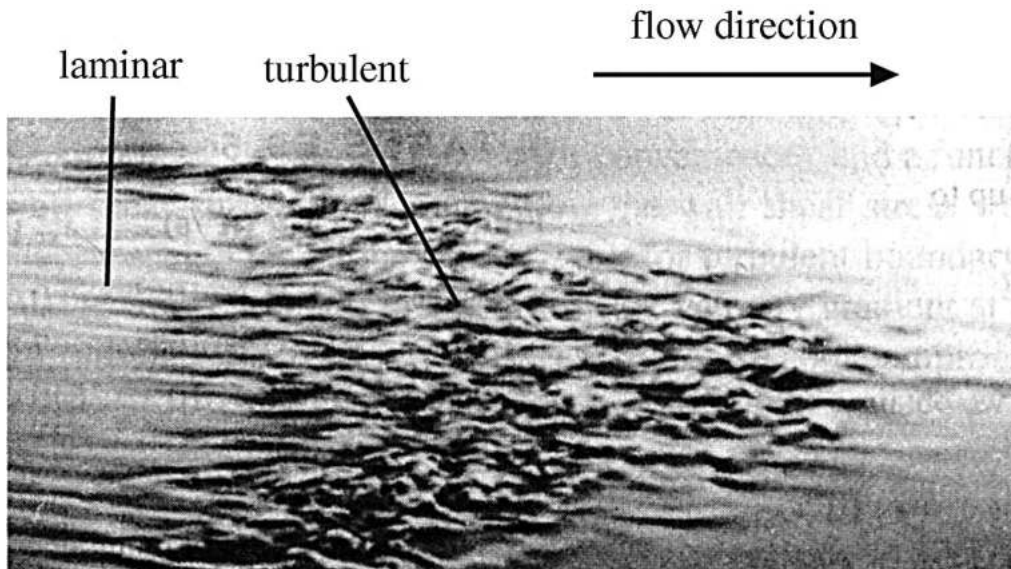
- **Example:** Determine the streamlines for flow near a stagnation point...the velocity is $\mathbf{u} = Ax\mathbf{i} - Ay\mathbf{j}$, where A is a constant.
 - For 2-D flow, $dy/dx = v/u = (-Ay)/(Ax) = -y/x$
 - Hence, $dx/x + dy/y = 0$
 - Integrating yields $\ln x + \ln y = \ln xy = \text{constant}$
 - Therefore, $xy = \text{constant}$...a family of hyperbolas.



Types of flow

Laminar and Turbulent Flow

- **Laminar flow:** a flow in which the fluid flows with no significant mixing of neighboring fluid particles. The flow may be steady or unsteady.
- **Turbulent flow:** a flow in which the fluid motions vary irregularly so that quantities such as velocity and pressure show a random variation with time and space coordinates.



Reynolds number

- Laminar flows are associated with low velocities and turbulent flows with high velocities. The parameter used to predict the flow regime is the **Reynolds number**.

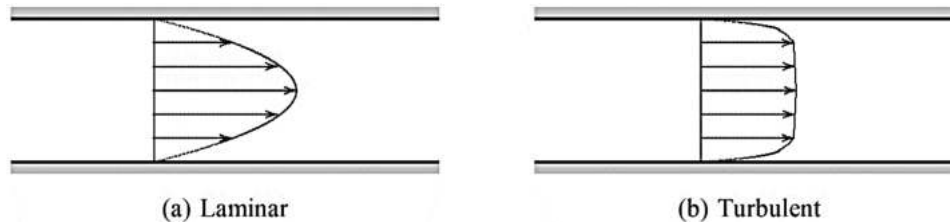
$$\text{Re} = \frac{\rho VL}{\mu} = \frac{VL}{\mu / \rho} = \frac{VL}{\nu}$$

where L and V are a characteristic length and velocity, respectively, and ν is the kinematic viscosity. For pipe flow, the characteristic length and velocity are the diameter and the mean velocity, respectively.

- There is a **critical Reynolds number** below which the flow is always laminar. For pipe flow, **$\text{Re}_{\text{crit}} = 2000$** .

Types of flow

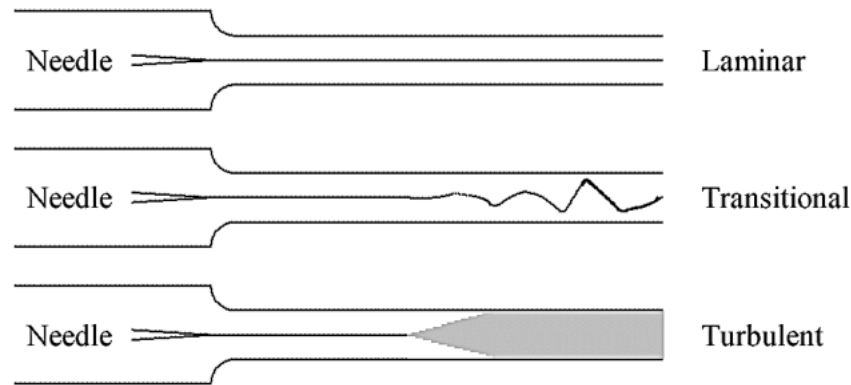
- As Reynolds number increases, all flows undergo a **transition** from **laminar** to **turbulent** motion.
- Turbulence is a **chaotic** phenomenon characterized by rapid fluctuations over a **wide range of frequencies** in all flow properties.



- Turbulence is present in most fluid flows of engineering interest:
 - Flow past airplanes, automobiles, ships, rockets
 - Flow in pipes, ducts, turbomachines, rivers, atmosphere
 - **Noteworthy example...**blood flow in a human body

Turbulence

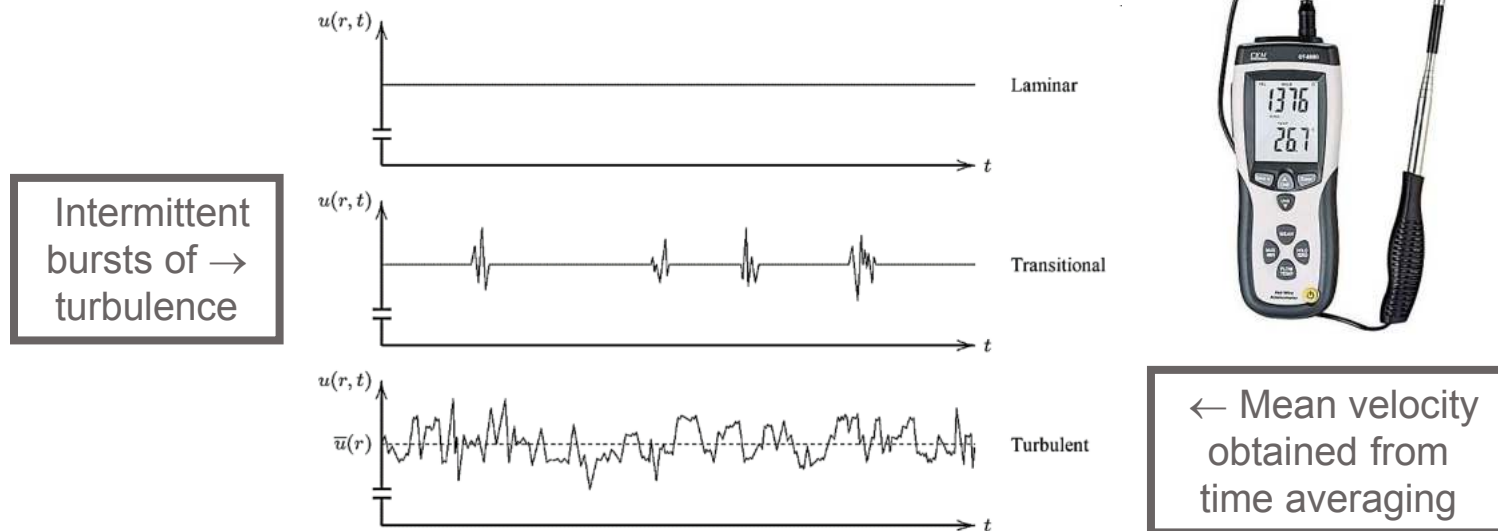
- **Reynolds** (1883) injected dye into fluid flowing in a transparent pipe and observed the following...



- The dye mixes very rapidly when the flow is turbulent...turbulent mixing can be very helpful for:
 - **Enhancing combustion in a rocket,**
 - **Improving efficiency of sewage-treatment plants,**
 - **Mixing cream and sugar with coffee...**

Turbulence

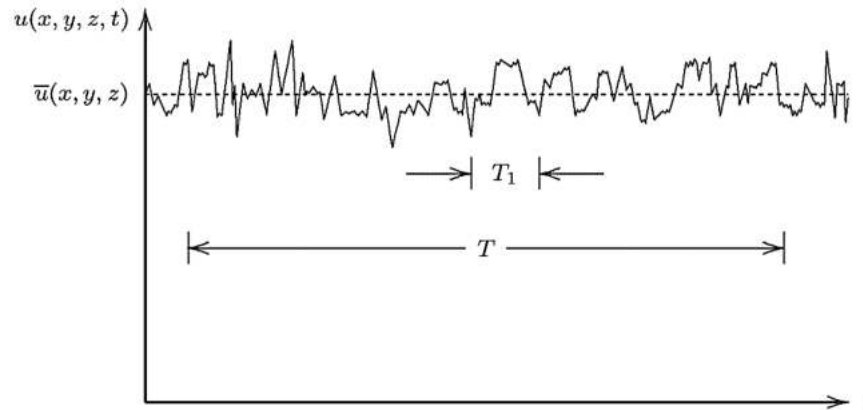
- Modern devices such as the hot-wire anemometer and the laser-Doppler velocimeter reveal the rapid turbulent fluctuations in flow properties



- Engineering approaches to turbulence focus on statistical averages...design methods depend heavily on empirical formulations.

Reynolds Averaging

- Turbulence consists of random fluctuations in all flow properties...statistical methods are needed.



- Decompose into mean and fluctuating parts:

$$\mathbf{u}(x, y, z, t) = \bar{\mathbf{u}}(x, y, z) + \mathbf{u}'(x, y, z, t)$$

- The **mean velocity** is calculated as:

$$\bar{\mathbf{u}}(x, y, z) = \lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T \mathbf{u}(x, y, z, t) dt$$

Acceleration and Euler's Equation

- Basing on Eulerian description:

$$a_x = \frac{Du}{Dt} = \underbrace{u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z}}_{\text{convective acceleration}} + \underbrace{\frac{\partial u}{\partial t}}_{\text{local acceleration}}$$

- Euler's equation concerns pressure variation in an accelerating fluid in which there is no velocity gradient within the fluid.

$$-\nabla p_z = \rho \mathbf{a}$$

$$-\left(\begin{array}{c} \text{gradient of} \\ \text{piezometric} \\ \text{pressure} \\ \text{field} \end{array} \right) = \left(\begin{array}{c} \text{mass} \\ \text{volume} \end{array} \right) \left(\begin{array}{c} \text{acceleration} \\ \text{of particle} \end{array} \right)$$

- Euler's equation can be applied in any direction in the fluid.
- Note that when there is no acceleration, the Euler's equation reduces to the hydrostatic pressure variation in a fluid ($p + \rho g z = \text{const.}$). In other words, along a direction in which there is no acceleration the pressure distribution is hydrostatic. For example, pressure variation normal to streamlines is hydrostatic.

Bernoulli Equation

The Bernoulli Equation along a Pathline/Streamline

- The Bernoulli equation is obtained from the integration of Euler's equation **along a streamline**. Assuming **steady incompressible inviscid flow**, the velocity of a particle depends on position only, i.e., $V = V(s)$.

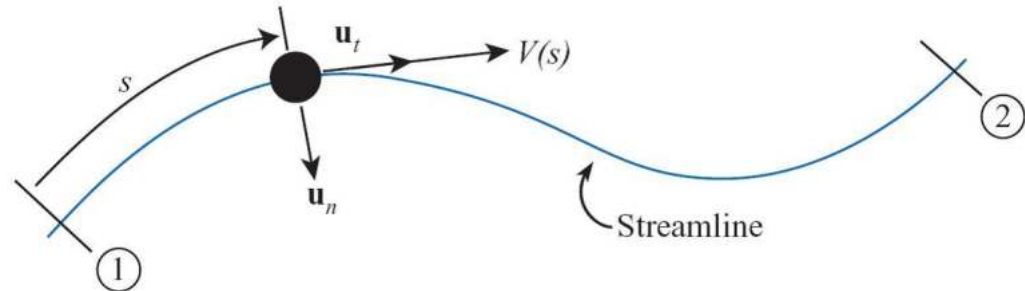
**Euler's
Equation**
:

$$-\frac{\partial}{\partial s}(p + \gamma z) = \rho a_t$$

$$\Rightarrow a_t = V \frac{\partial V}{\partial s} + \frac{\partial V}{\partial t} = V \frac{\partial V}{\partial s}$$

$$\Rightarrow -\frac{d}{ds}(p + \gamma z) = \rho V \frac{dV}{ds} = \rho \frac{d}{ds} \left(\frac{V^2}{2} \right) = \frac{d}{ds} \left(\rho \frac{V^2}{2} \right)$$

$$\Rightarrow \frac{d}{ds} \left(p + \gamma z + \rho \frac{V^2}{2} \right) = 0 \Rightarrow \boxed{p + \gamma z + \rho \frac{V^2}{2} = \text{const}}$$



Bernoulli Equation

The Bernoulli Equation along a Streamline

- The Bernoulli equation is stated in any of the following forms:

Pressure form: $\underbrace{p + \gamma z}_{\text{piezometric pressure}} + \underbrace{\frac{1}{2} \rho V^2}_{\text{kinetic pressure}} = \text{constant along a streamline}$

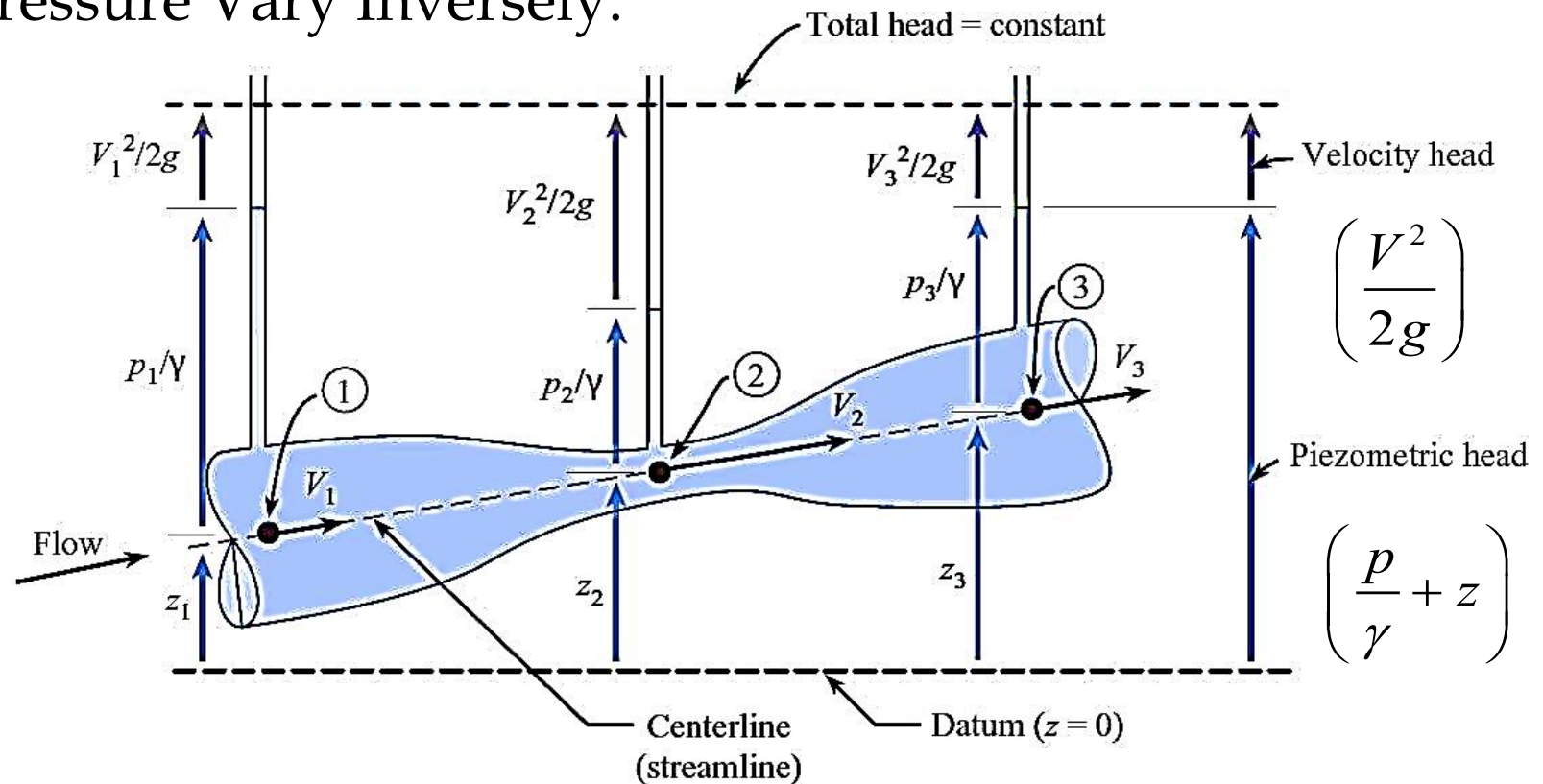
Head form: $\underbrace{\frac{p}{\gamma} + z}_{\text{piezometric head}} + \underbrace{\frac{V^2}{2g}}_{\text{velocity head}} = \text{constant along a streamline}$

Note: The kinetic pressure ($\rho V^2/2$) is also called **dynamic pressure**.

- **Head:** a term used to characterize the balance of work and energy in a flowing fluid.
- **Velocity Head:** characterizes the kinetic energy in a flowing fluid
- **Elevation Head:** characterizes the gravitational potential energy of a fluid
- **Pressure Head:** relates work done by pressure forces.

Bernoulli Equation

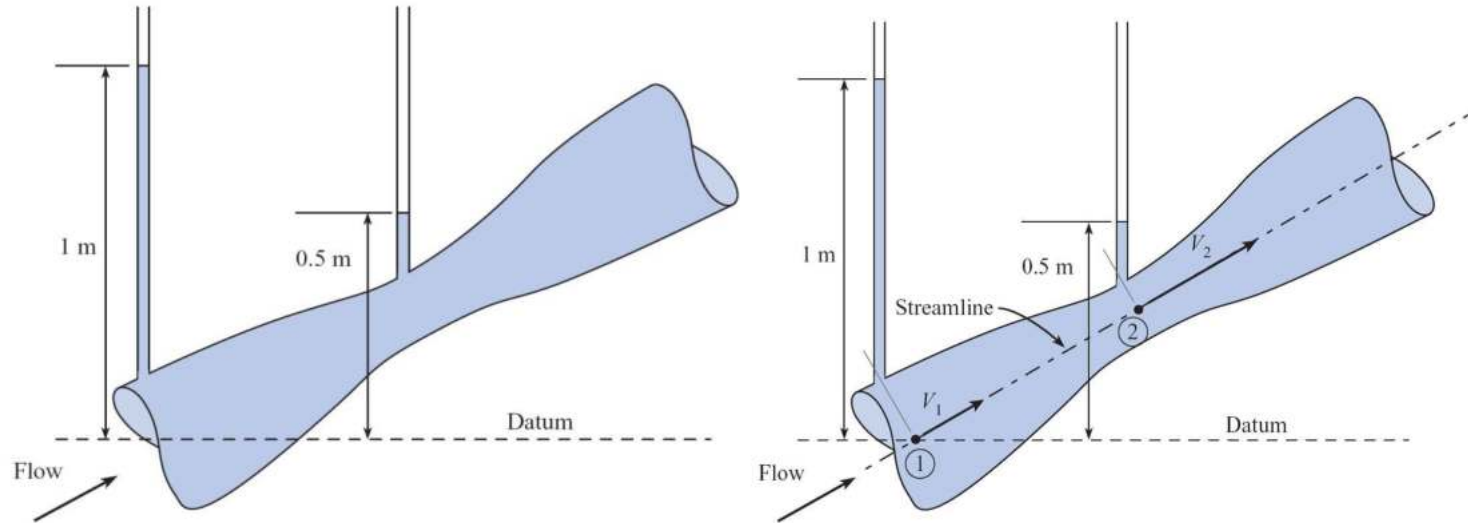
- Physical Interpretation 01: Energy is Conserved
- Physical Interpretation 02: Velocity & Piezometric Pressure Vary Inversely.



Bernoulli Equation

■ Example:

We assume
that: $V_1 = \frac{V_2}{2}$



$$\frac{p_1}{\gamma} + z_1 + \frac{V_1^2}{2g} = \frac{p_2}{\gamma} + z_2 + \frac{V_2^2}{2g} \Rightarrow \boxed{h_1 + \frac{V_1^2}{2g} = h_2 + \frac{V_2^2}{2g}}$$

$$\therefore (1.0 \text{ m}) + \frac{V_1^2}{2g} = (0.5 \text{ m}) + \frac{V_2^2}{2g}, \quad V_1 = 0.5V_2$$

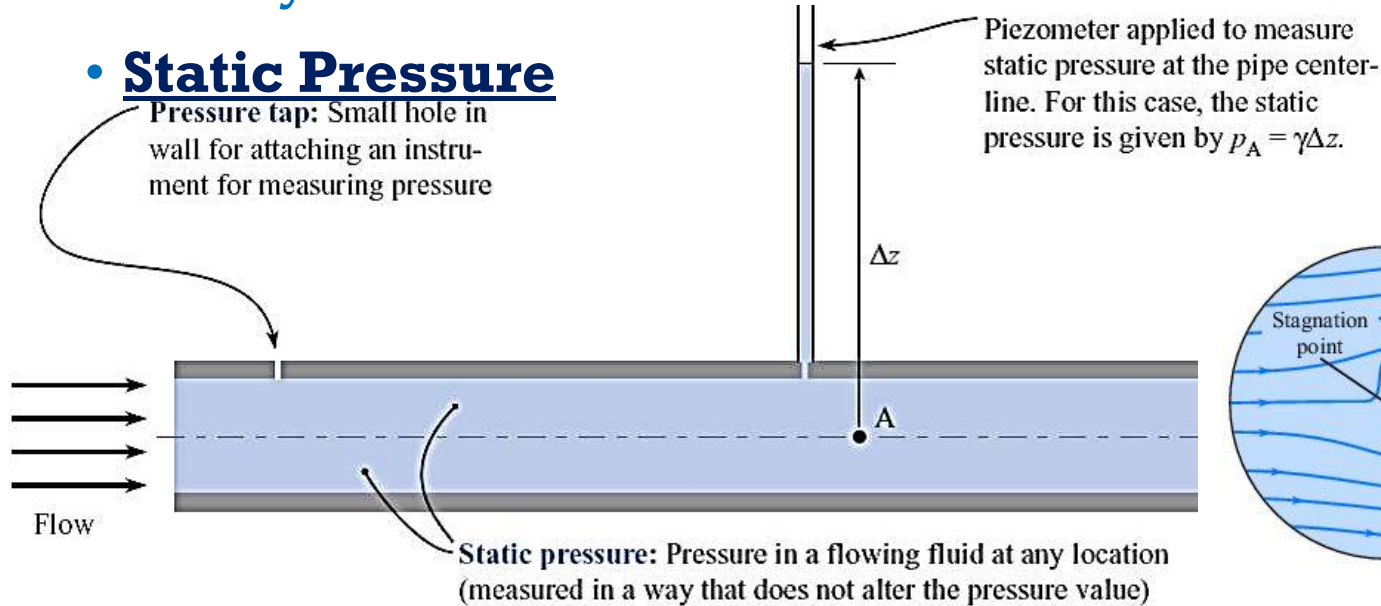
$$\Rightarrow (1.0 \text{ m}) + \frac{(0.5V_2)^2}{2g} = (0.5 \text{ m}) + \frac{V_2^2}{2g} \Rightarrow \frac{0.75V_2^2}{2g} = (0.5 \text{ m})$$

Application of Bernoulli Equation

Velocity and Pressure Measurement

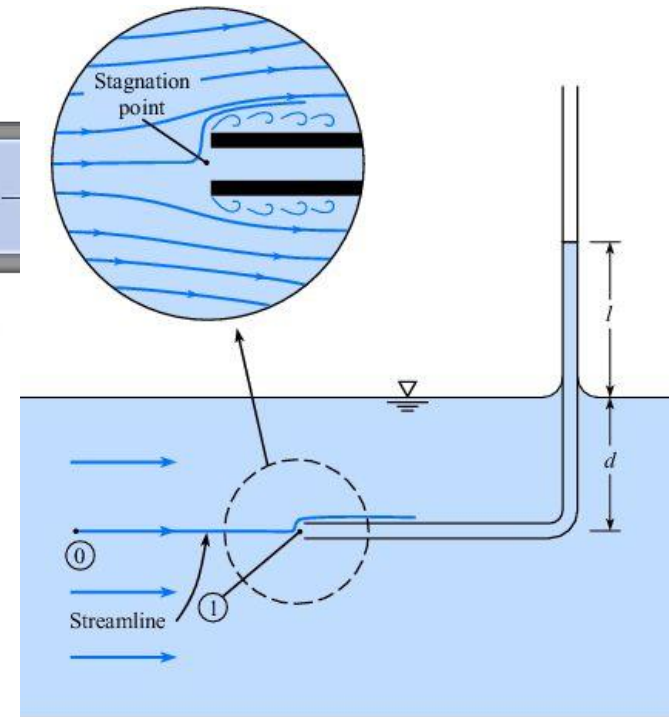
- **Static Pressure**

Pressure tap: Small hole in wall for attaching an instrument for measuring pressure



- **Stagnation Tube**

Also known as **total head tube** is an open-ended tube directed upstream in a flow as shown.



Application of Bernoulli Equation

- Stagnation Tube

Applying Bernoulli equation:

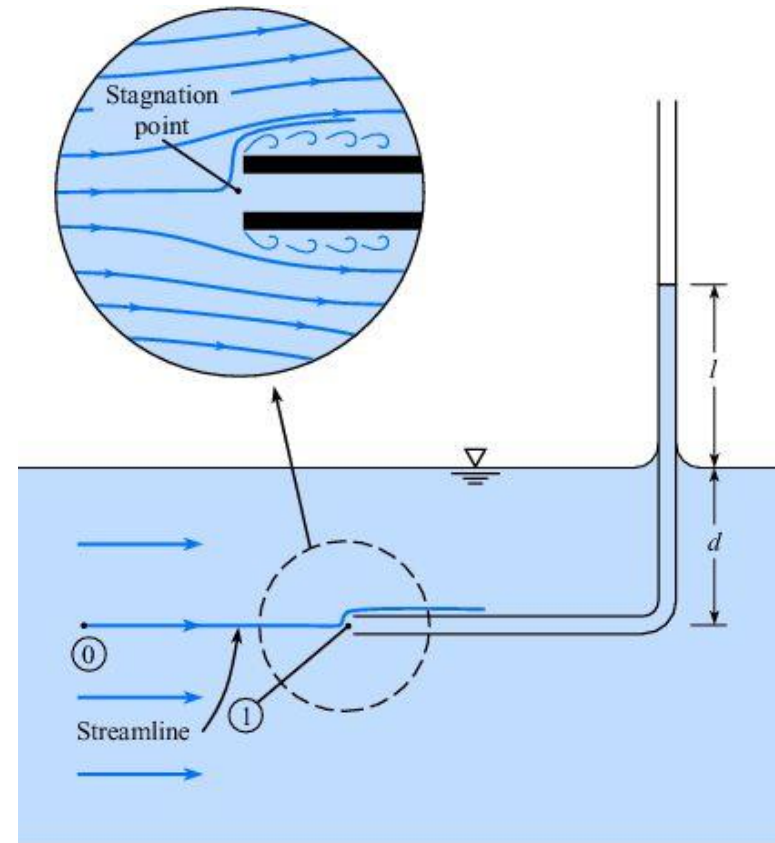
$$p_1 + \rho \frac{V_1^2}{2} = p_0 + \rho \frac{V_0^2}{2}; \quad V_1 = 0$$

$$\Rightarrow V_0 = \sqrt{\frac{2(p_1 - p_0)}{\rho}}$$

Applying the hydrostatic equation:

$$\therefore V_0 = \sqrt{\frac{2(\gamma l)}{\rho}} \Rightarrow V_0 = \sqrt{2gl}$$

Note: The stagnation tube is not suitable for velocity measurement in a pressurized pipe



Application of Bernoulli Equation

□ Pitot Tube

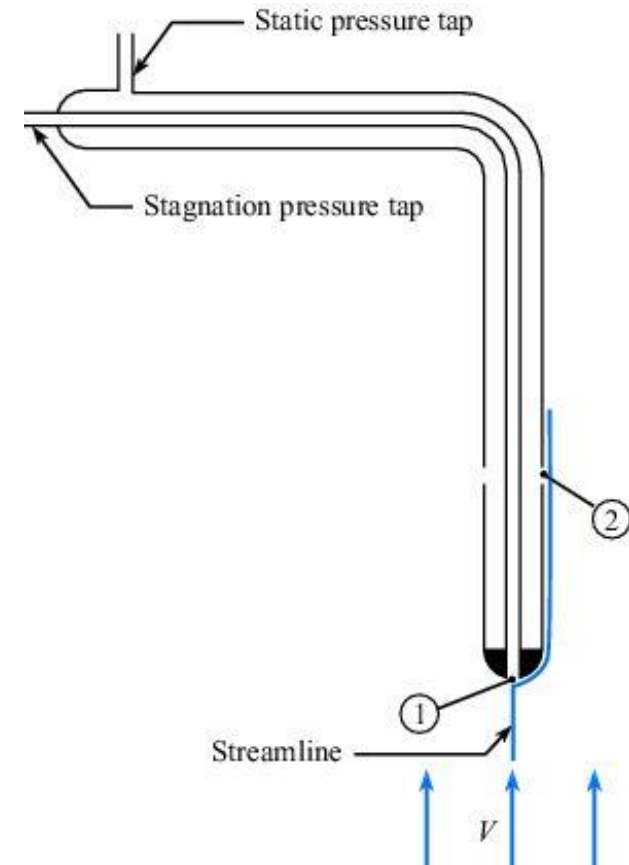
The pitot tube is used to measure the **local flow velocity** at a given point in the flow stream and **not the average flow velocity** in the pipe.

The Pitot tube has a pressure tap at the upstream end of the tube for sensing the stagnation pressure. It also has ports for sensing static pressure in the fluid.

Applying the Bernoulli equation gives:

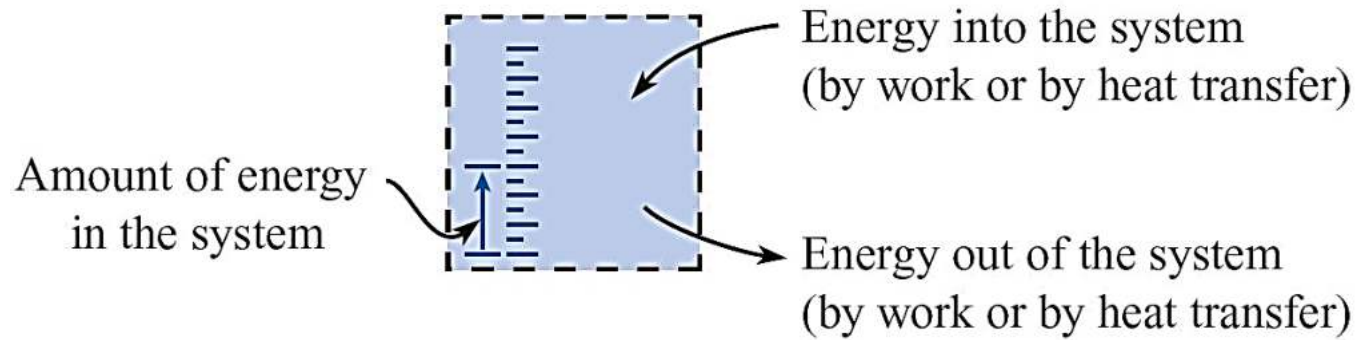
$$p_1 + \gamma z_1 + \rho \frac{V_1^2}{2} = p_2 + \gamma z_2 + \rho \frac{V_2^2}{2}; \quad V_1 = 0, V_2 = V$$

$$\Rightarrow V = \sqrt{\frac{2}{\rho}(p_{z,1} - p_{z,2})}$$



Modified-Bernoulli Equation

- **Joule's Theory of Energy Conservation:** The energy (property) of a closed system can be changed in only two ways:
 - **Work:** by work interactions at the boundary.
 - **Heat transfer:** by heat transfer (interaction) across the boundary.



- **First Law of Thermodynamics:** The work & energy balance proposed by Joule:

$$\Delta E = Q - W$$

- To modify the above equation so that it applies at an instant in time, take the derivative to give:

$$\frac{dE}{dt} = \dot{Q} - \dot{W}$$

Modified-Bernoulli Equation

Simplified forms of the energy principle

- For **non-uniform velocity distribution** at the inlet and outlet ports, the kinetic energy correction factor α is introduced to account for the velocity distribution. Energy equation is then written (after dividing through by $\dot{m}$) as:

$$\frac{1}{\dot{m}} \left(\dot{Q} - \dot{W}_{\text{shaft}} \right) + \left(\frac{p_1}{\rho} + gz_1 + u_1 + \alpha_1 \frac{\bar{V}_1^2}{2} \right) = \left(\frac{p_2}{\rho} + gz_2 + u_2 + \alpha_2 \frac{\bar{V}_2^2}{2} \right)$$

where $\bar{V}_1$ and $\bar{V}_2$ are the mean velocities at the inlet and outlet ports.

The kinetic energy correction factor, α , is defined by

$$\alpha = \frac{1}{A} \int_A \left(\frac{V}{\bar{V}} \right)^3 dA$$

- Thus, $\alpha = 1$ when the velocity is uniform across the section. For most cases of turbulent flow, $\alpha \approx 1.05$ and therefore it is common practice in engineering applications to let $\alpha = 1$.

Modified-Bernoulli Equation

Simplified forms of the energy principle

- The **shaft-work** term in energy equation is usually the result of a **turbine** or **pump** in the flow system. It is convenient to represent the shaft-work term as

$$\dot{W}_s = \dot{W}_t - \dot{W}_p$$

where $\dot{W}_t$ and $\dot{W}_p$ are the magnitudes of power delivered by a turbine or supplied to a pump, respectively.

- It is often conventional to express the term associated with a pump and a turbine as the **pump head** (h_p) and the **turbine head** (h_t), respectively, defined as

$$h_p = \frac{\text{work/time done by pump on flow}}{\text{weight/time of flowing fluid}} = \frac{\dot{W}_p}{\dot{m} g} \mapsto \text{head added by pump}$$
$$h_t = \frac{\text{work/time done by flow on turbine}}{\text{weight/time of flowing fluid}} = \frac{\dot{W}_t}{\dot{m} g} \mapsto \text{head removed by turbine}$$

Modified-Bernoulli Equation

Simplified forms of the energy principle

- Introducing the **pump head** (h_p) and the **turbine head** (h_t) terms in the energy equation yields after some re-arrangement:

$$\frac{p_1}{\gamma} + \alpha_1 \frac{\bar{V}_1^2}{2g} + z_1 + h_p = \frac{p_2}{\gamma} + \alpha_2 \frac{\bar{V}_2^2}{2g} + z_2 + h_t + \left[\frac{1}{g} (u_2 - u_1) - \frac{\dot{Q}}{\dot{m}g} \right]$$

- The last term enclosed in square brackets in the above equation represents energy loss due to **viscous action** between fluid particles and due to **heat transfer**. It is simply referred to as the **head loss** and is represented by (h_L). It is **always positive** because of second law of thermodynamics. Thus, the **final form of the energy equation** is:

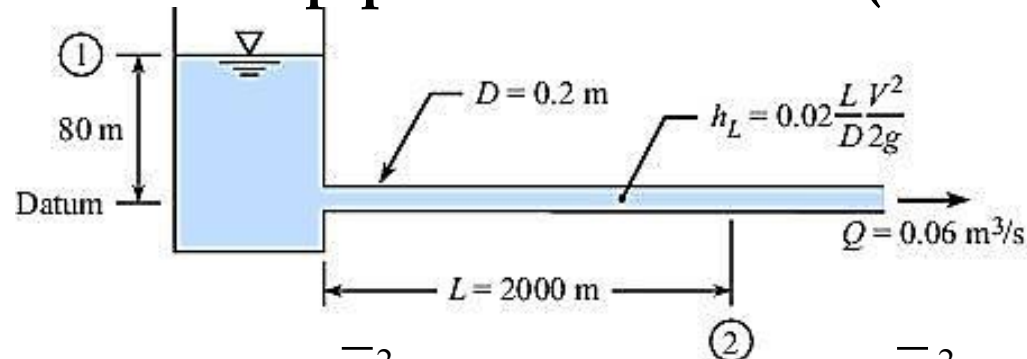
$$\boxed{\frac{p_1}{\gamma} + \alpha_1 \frac{\bar{V}_1^2}{2g} + z_1 + h_p = \frac{p_2}{\gamma} + \alpha_2 \frac{\bar{V}_2^2}{2g} + z_2 + h_t + h_L}$$

Modified-Bernoulli Equation

Example :

- To find the pressure in pipe at location 2 (2000 m from reservoir)

Solution:



The energy equation:
$$\frac{p_1}{\gamma} + \alpha_1 \frac{\bar{V}_1^2}{2g} + z_1 + h_p = \frac{p_2}{\gamma} + \alpha_2 \frac{\bar{V}_2^2}{2g} + z_2 + h_t + h_L$$

$$z_1 = 100 \text{ m}, z_2 = 20 \text{ m}, \alpha_2 = 1, Q = 0.06 \text{ m}^3/\text{s}$$

Data:

$$p_1 = 0 \text{ gage}, V_1 \approx 0 \text{ reservoir level nearly constant}, h_p = h_t = 0$$

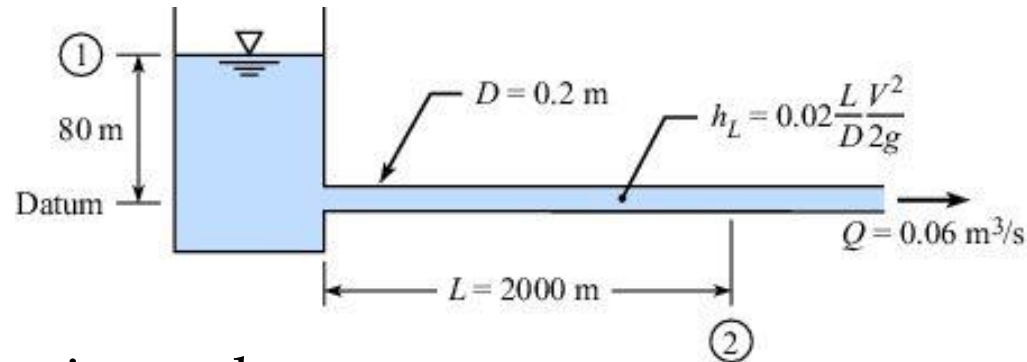
Term-by-term analysis:

Modified-Bernoulli Equation

Example :

- To find the pressure in pipe at location 2 (2000 m from reservoir)

Solution:



The energy equation reduces to:

$$z_1 - z_2 = \frac{p_2}{\gamma} + \frac{V_2^2}{2g} + h_L \Rightarrow \frac{p_2}{\gamma} = \left(z_1 - z_2 - \frac{V_2^2}{2g} - h_L \right)$$

where: $\bar{V}_2 = V_2 = \frac{Q}{A} = 1.910 \text{ m/s}$, $h_L = \frac{0.02(L/D)V_2^2}{2g} = 37.2 \text{ m}$

Thus:
$$p_2 = \gamma \left(z_1 - z_2 - \frac{V_2^2}{2g} - h_L \right) = 418 \text{ kPa}$$